## Removing the blindfold

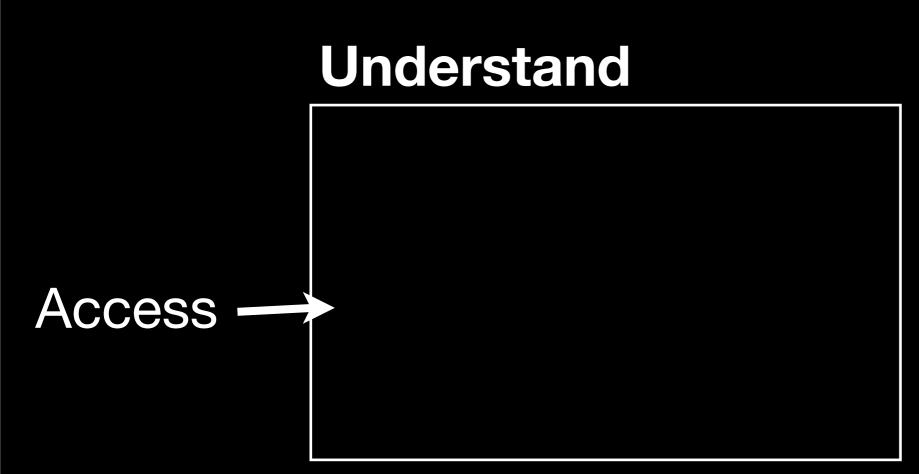
Visualising statistical models

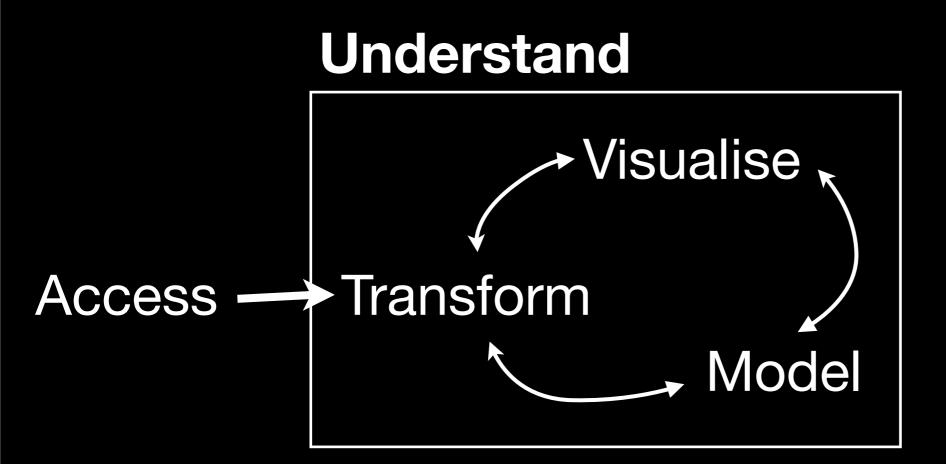
#### **Hadley Wickham**

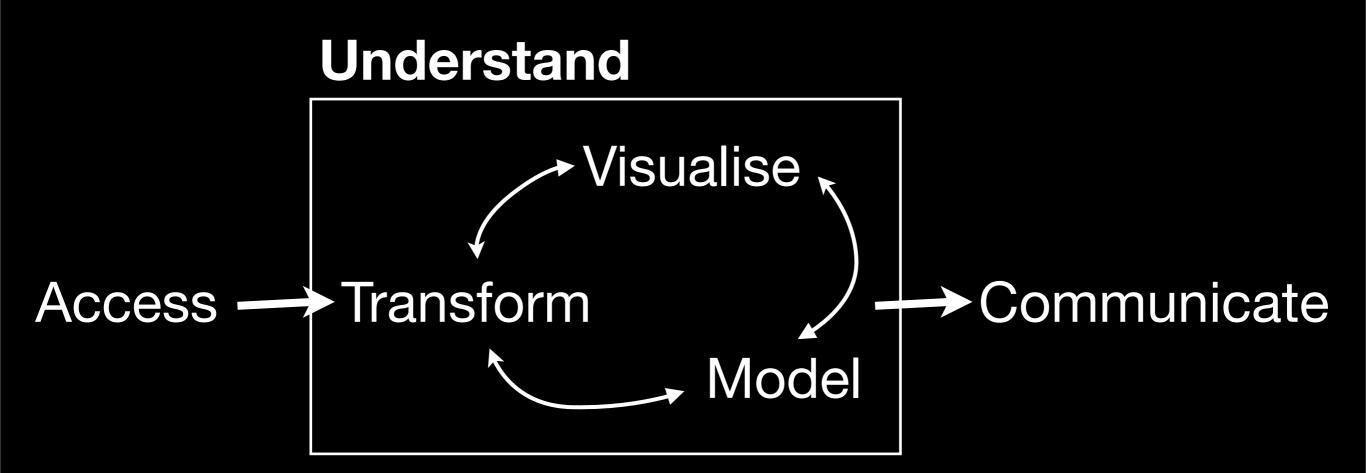
Assistant Professor Dobelman Family Junior Chair Department of Statistics Rice University

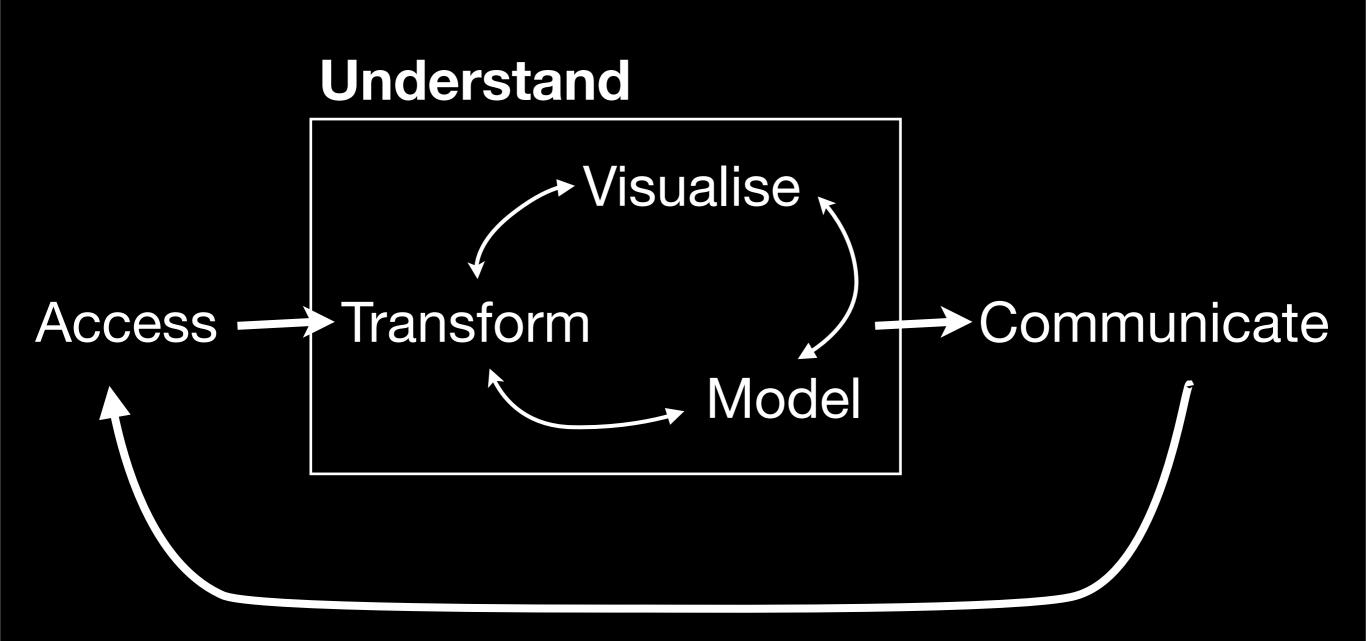


#### Access

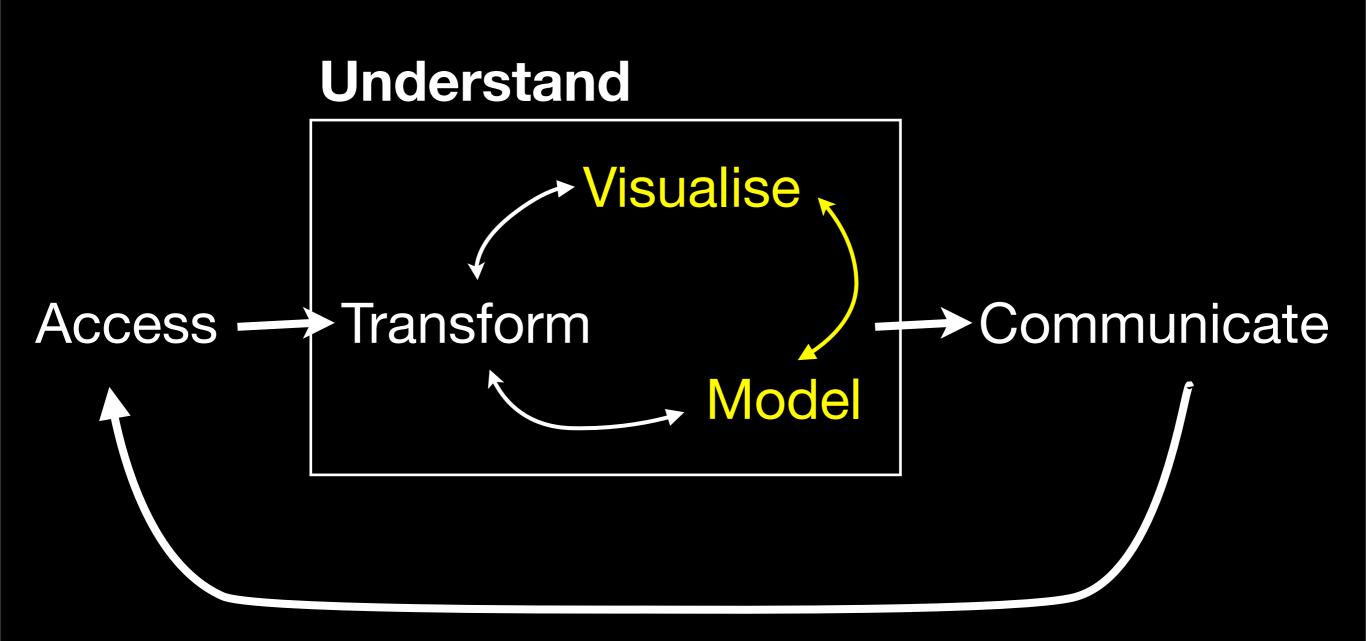








| Visualisation   | Model  |
|---|--|
| <ul> <li>+ Uncovers the unexpected</li> <li>- Slow</li> <li>- Cognitive biases</li> </ul> | <ul> <li>+ Mathematically<br/>well founded</li> <li>+ Fast</li> <li>- Only discovers<br/>what we<br/>anticipate</li> </ul> |



## Neural networks

### Display the model in the data space

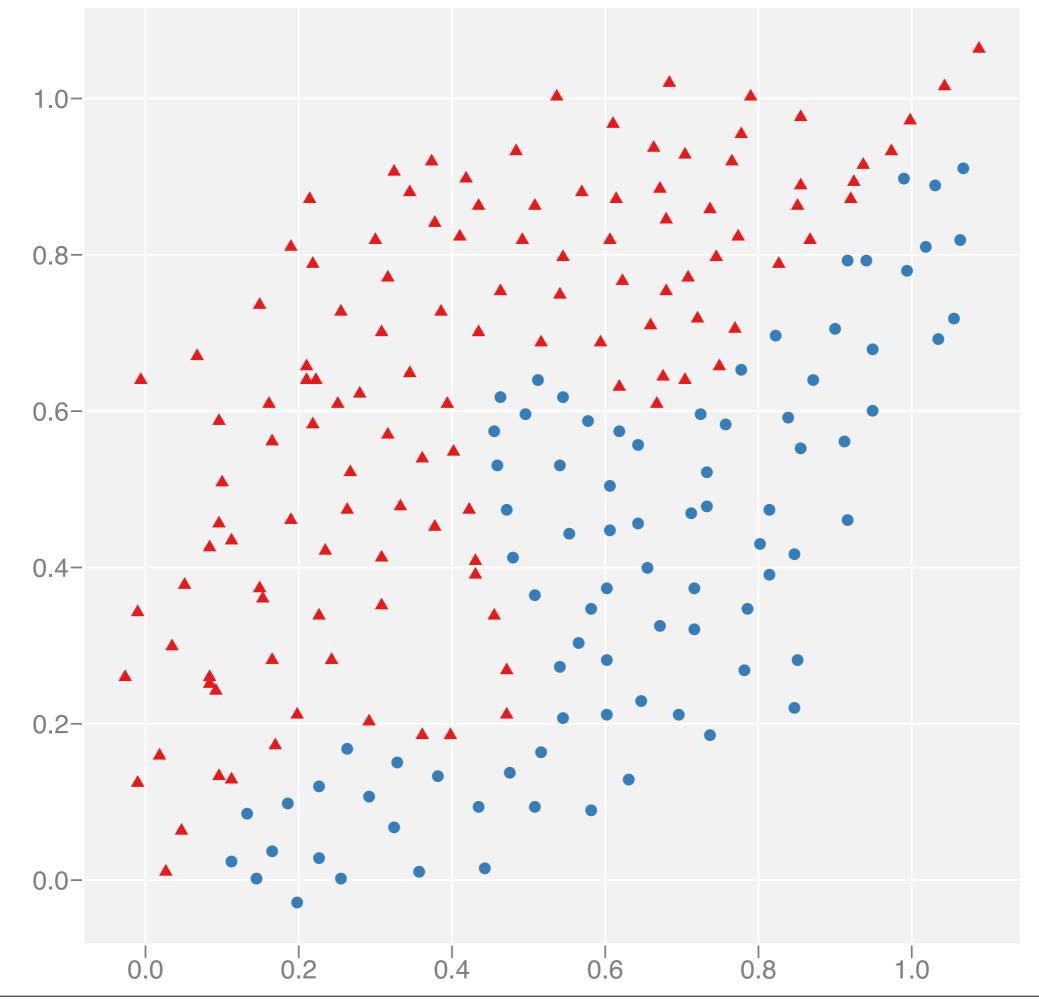
### Look at many members of a collection

Explore the process of fitting, not just the end result

## Neural networks

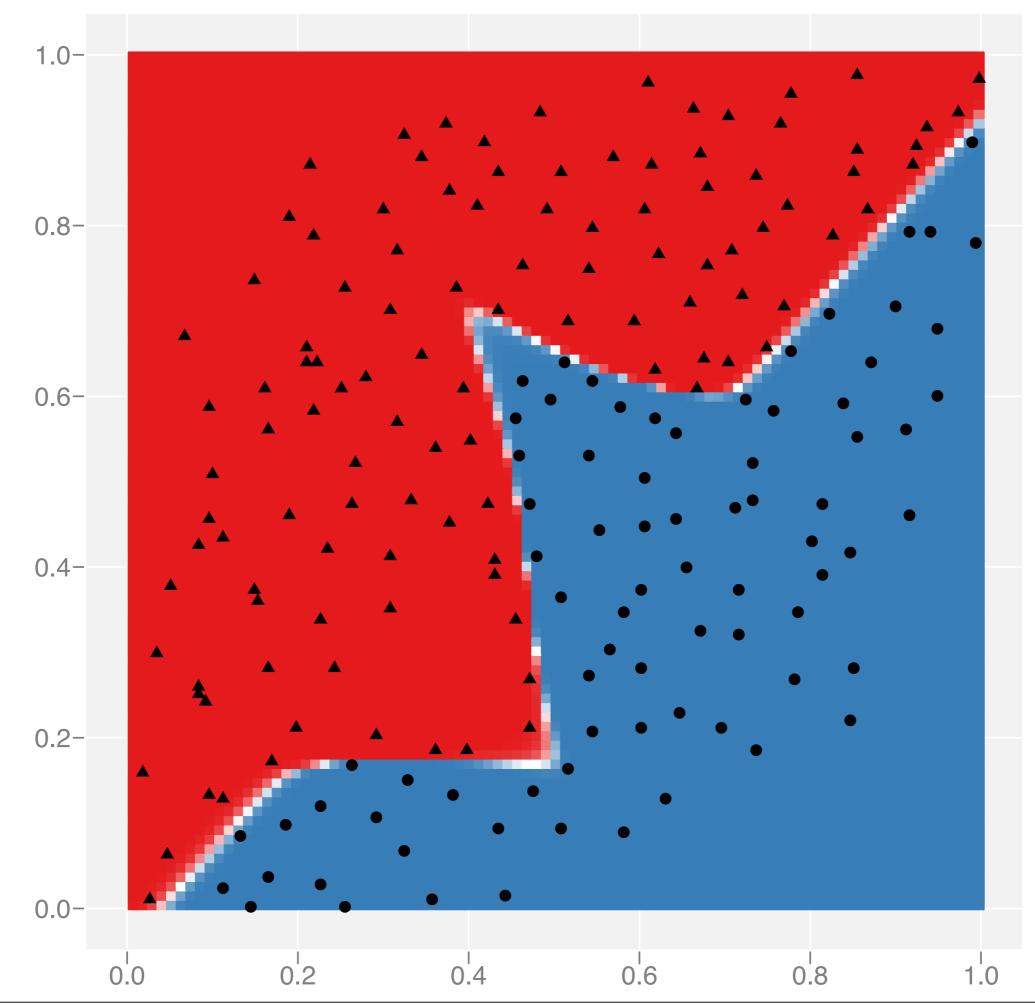
- Modelled on the way that brains work
- Normally treated as a black box. Can we gain more insight into how they work?

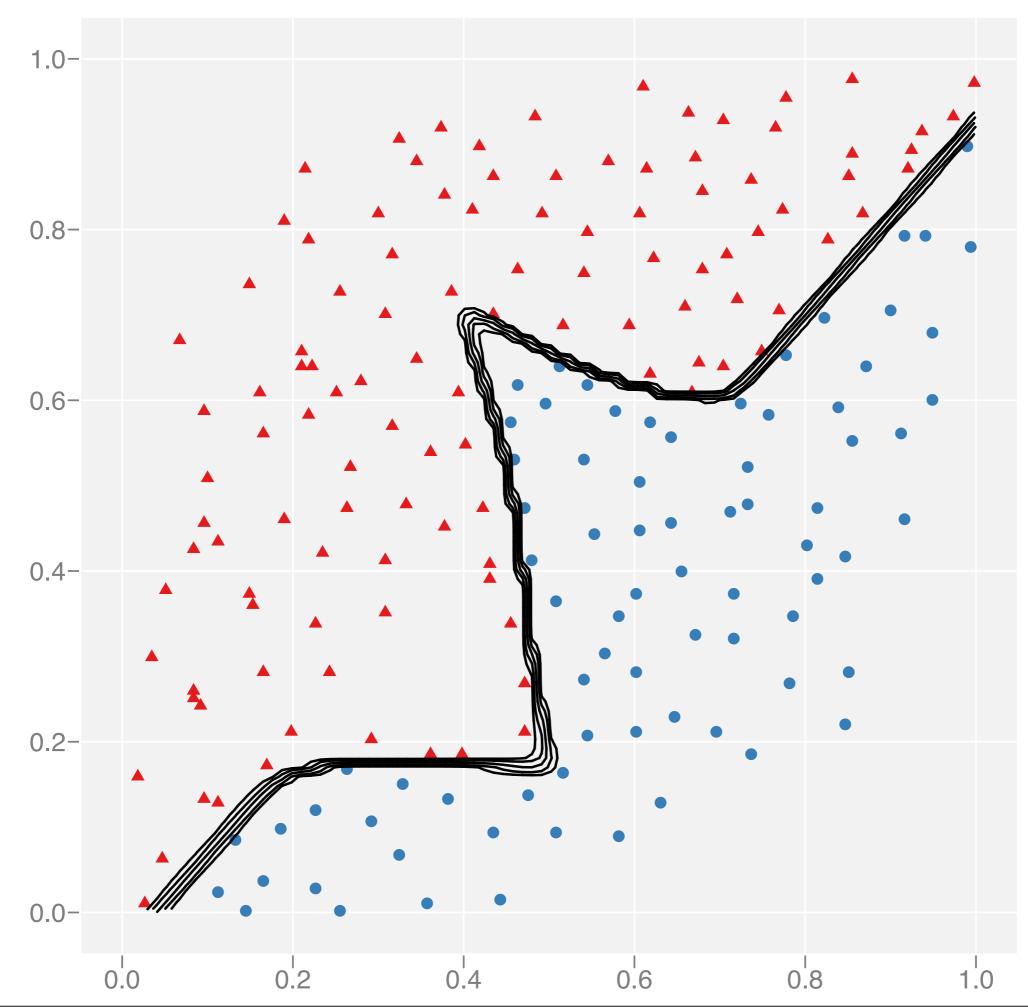
• Single hidden-layer neural network: nnet R package

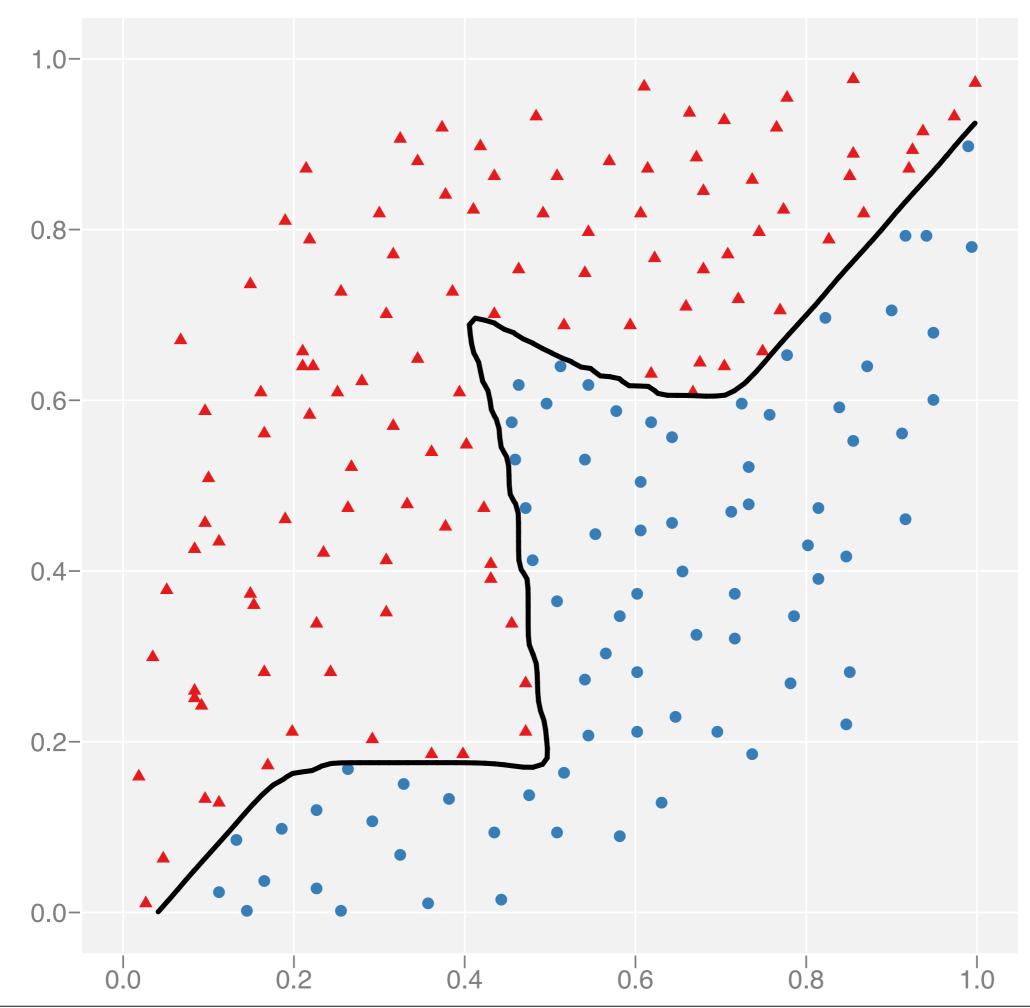


# Display the model in data space

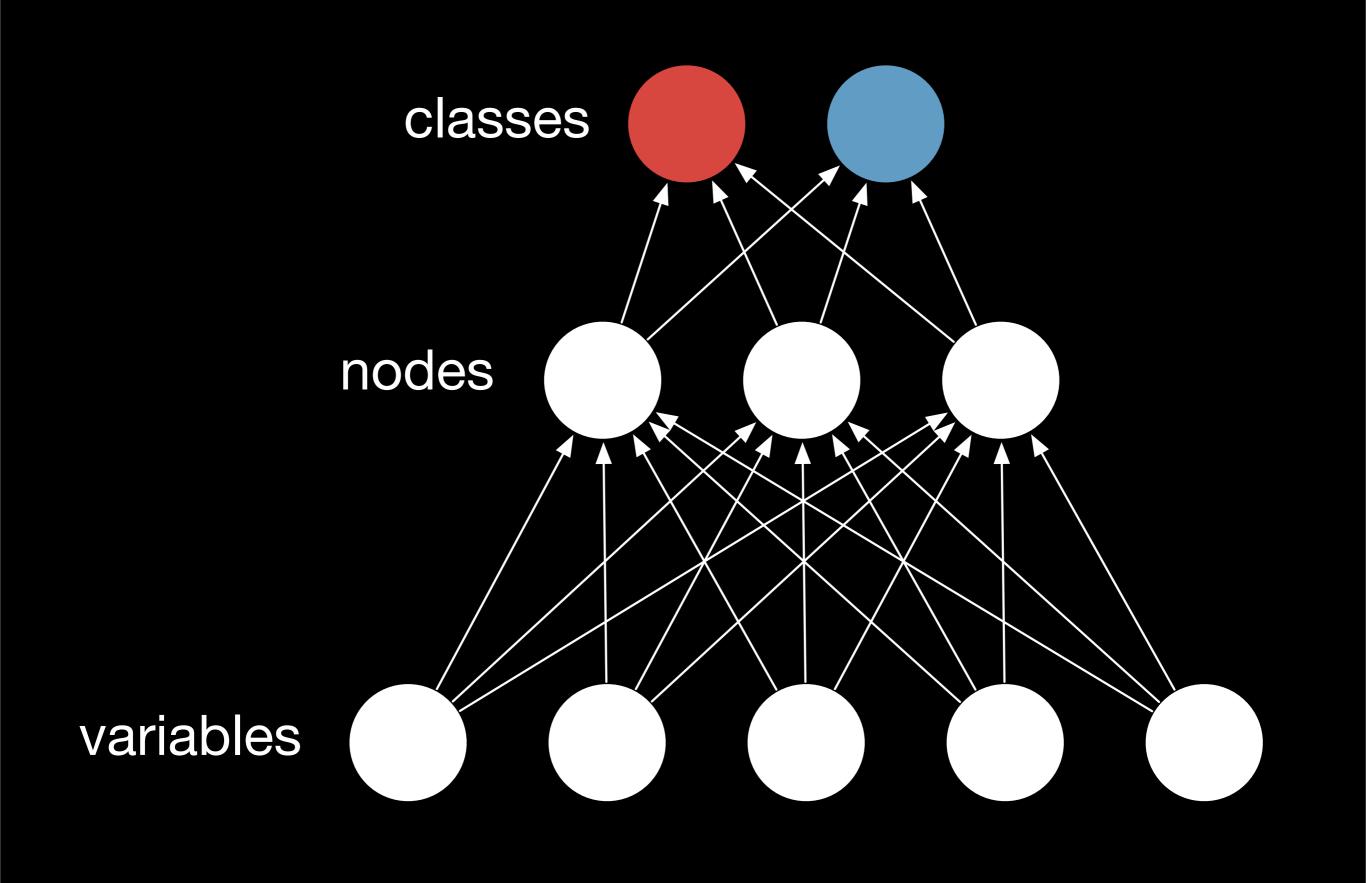


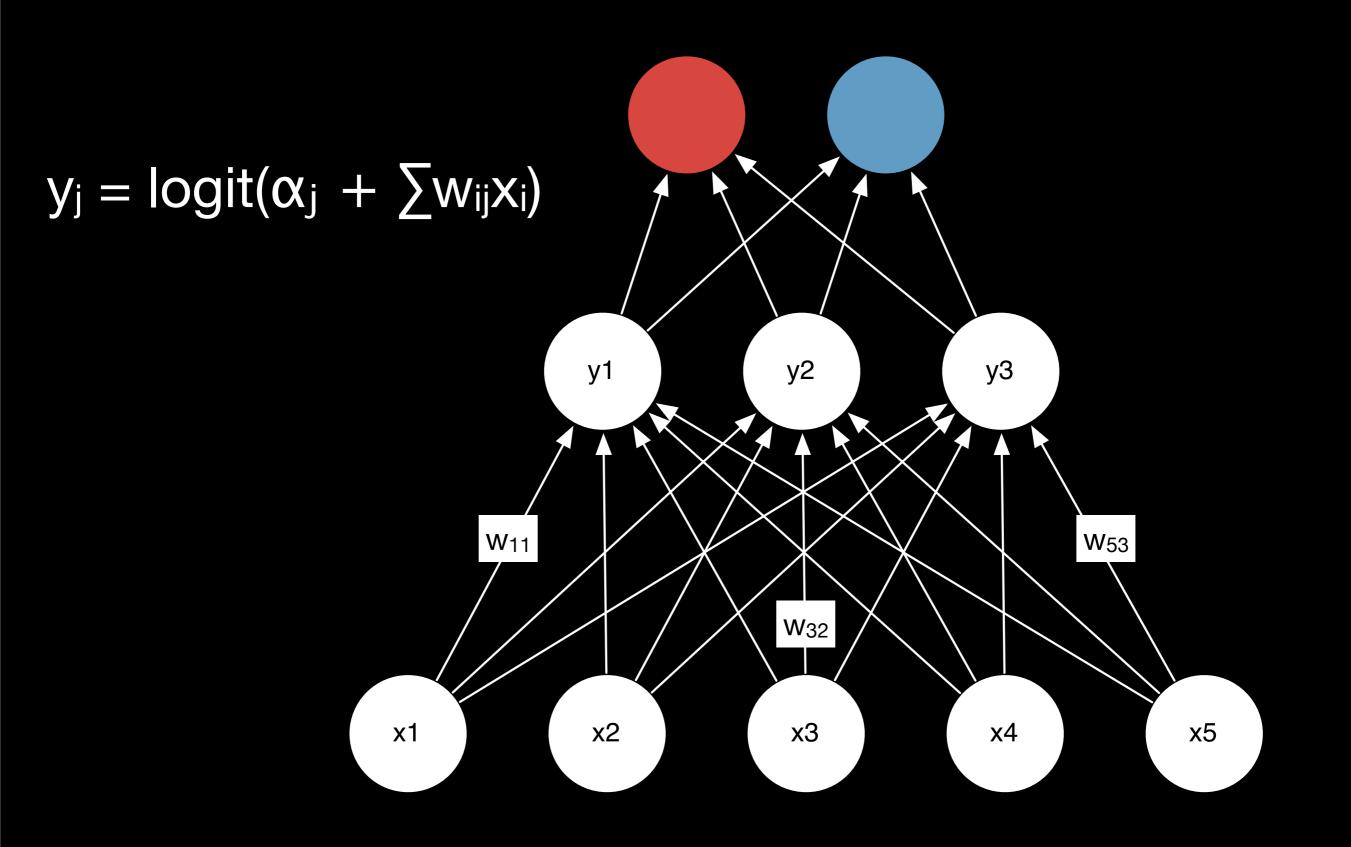


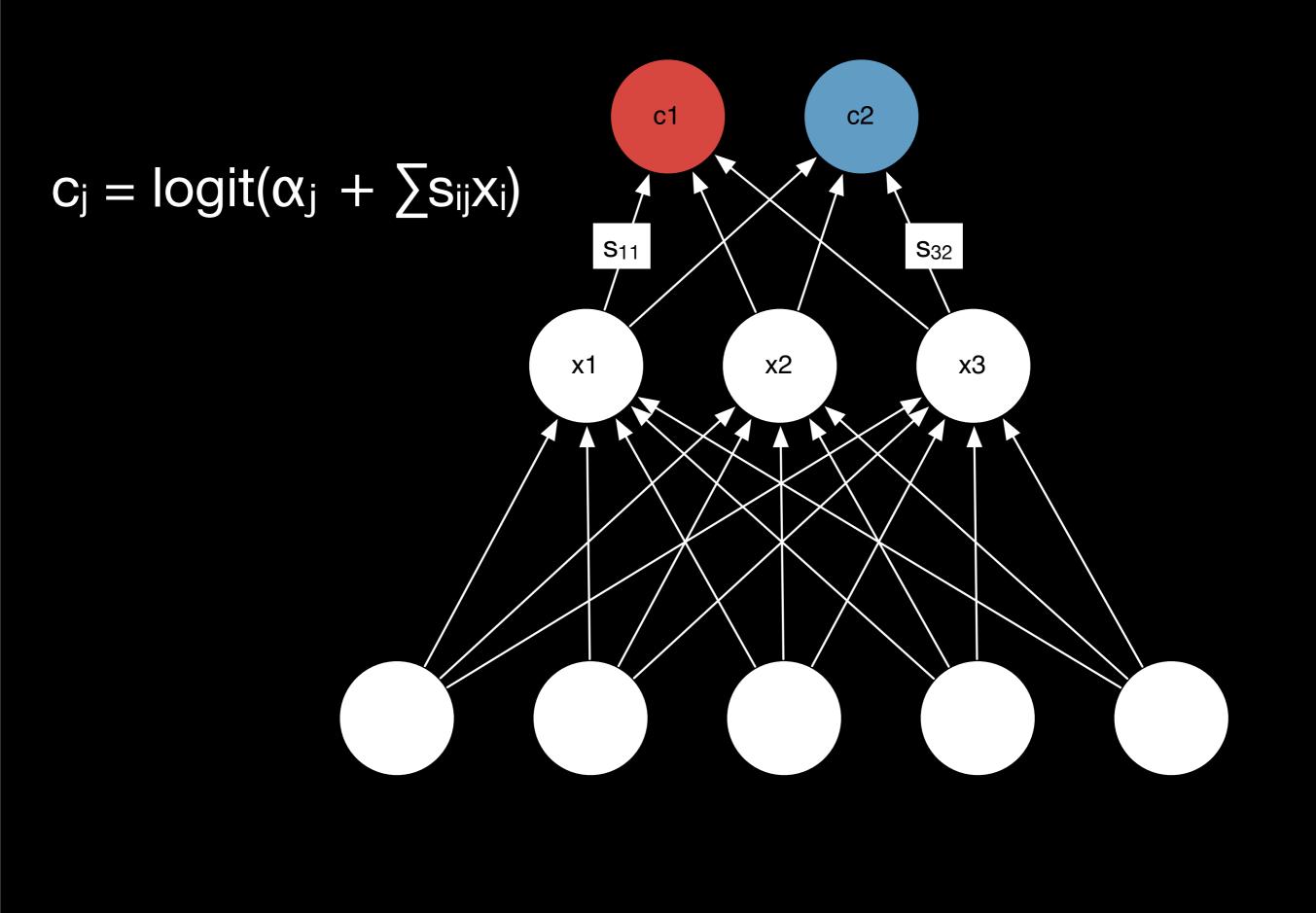


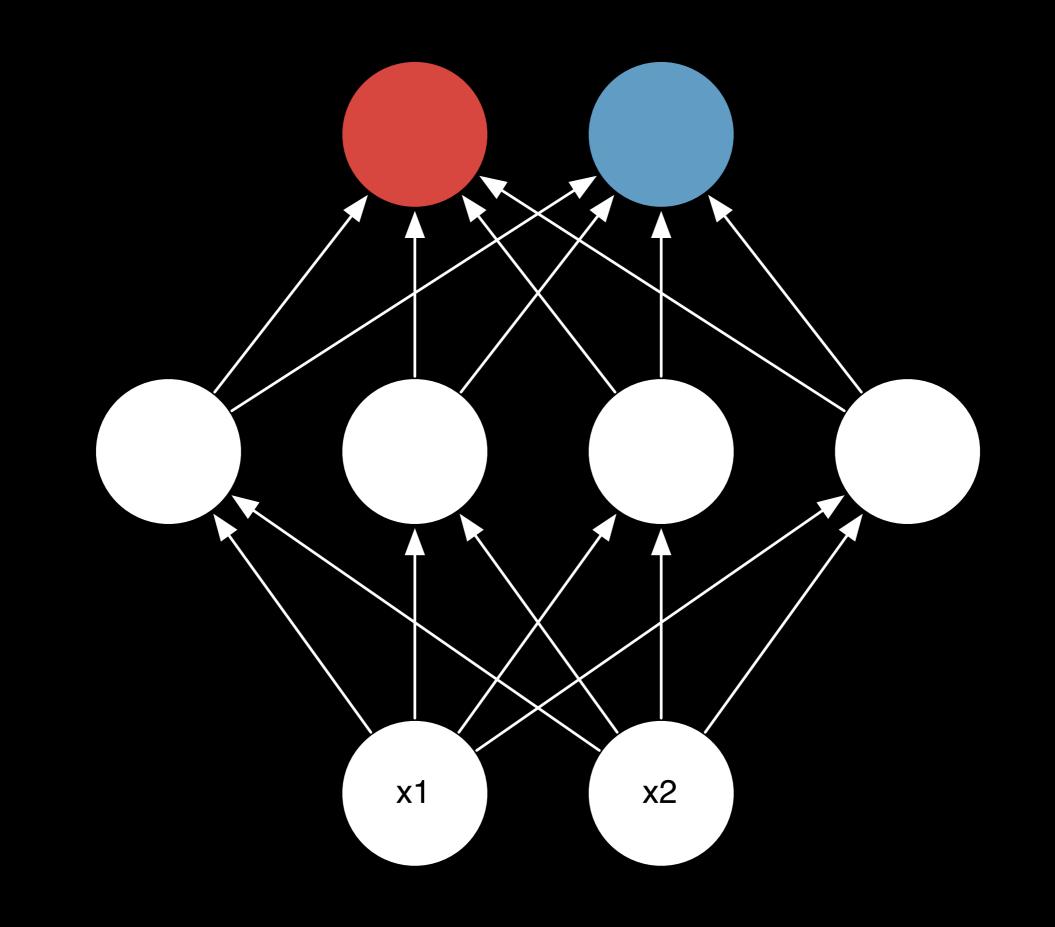


## How do neural networks work?

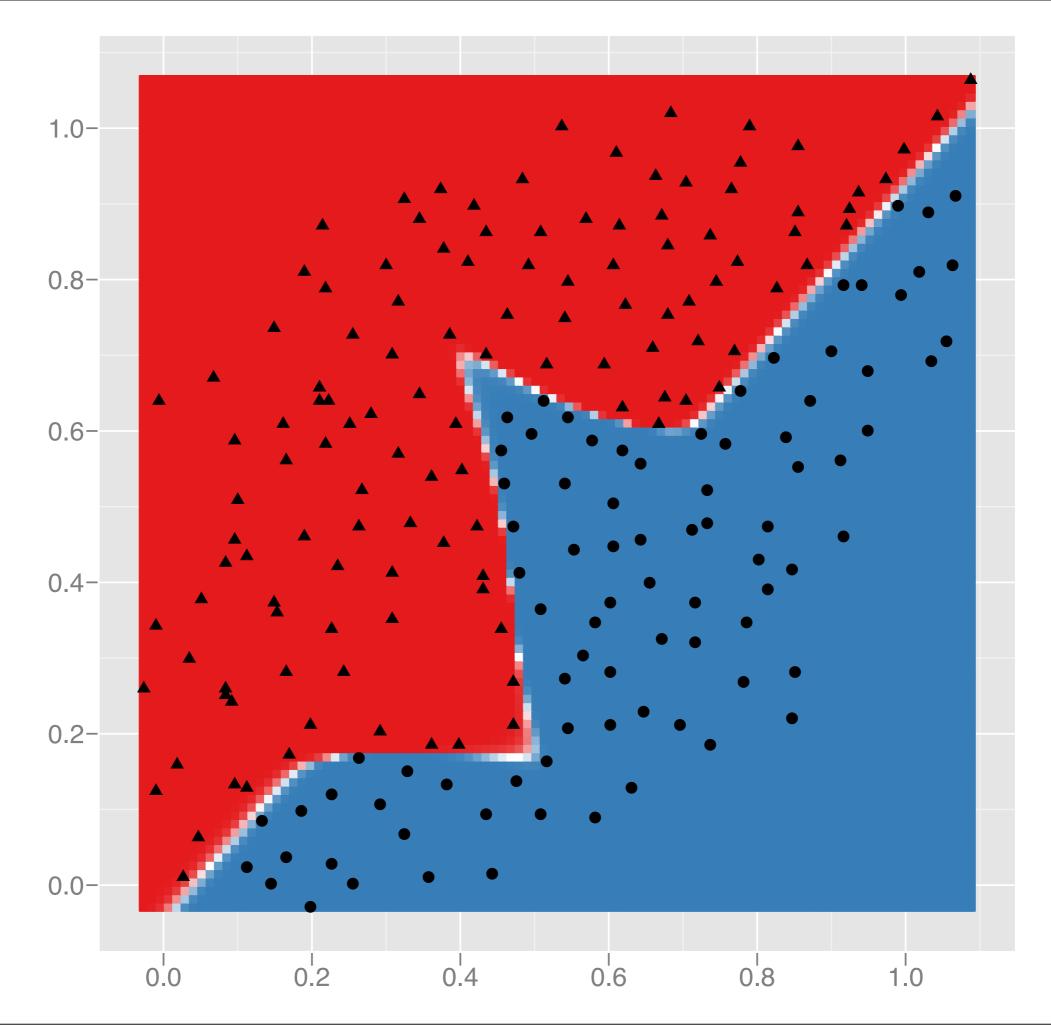


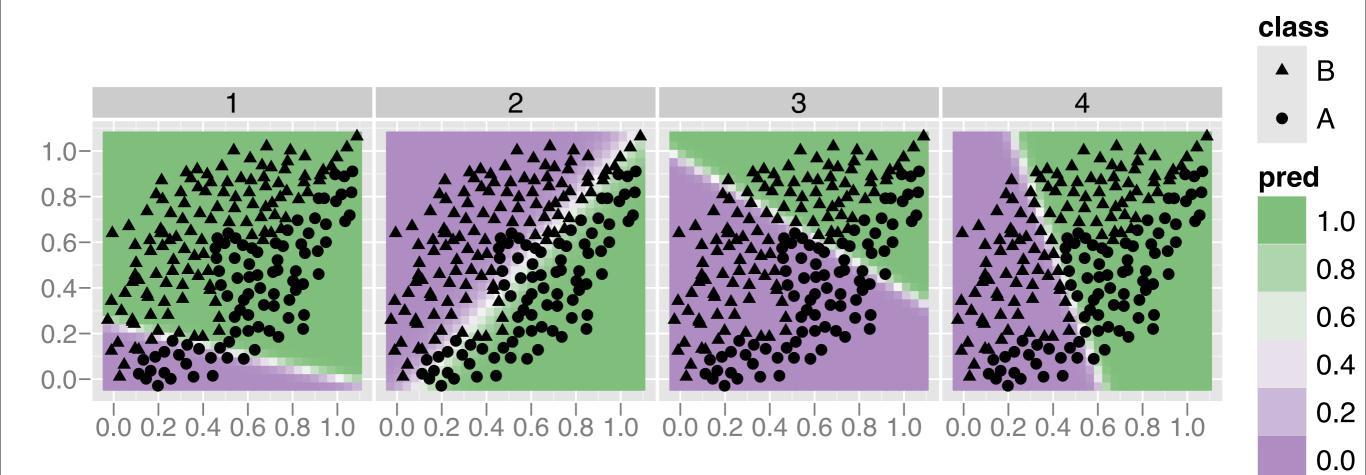


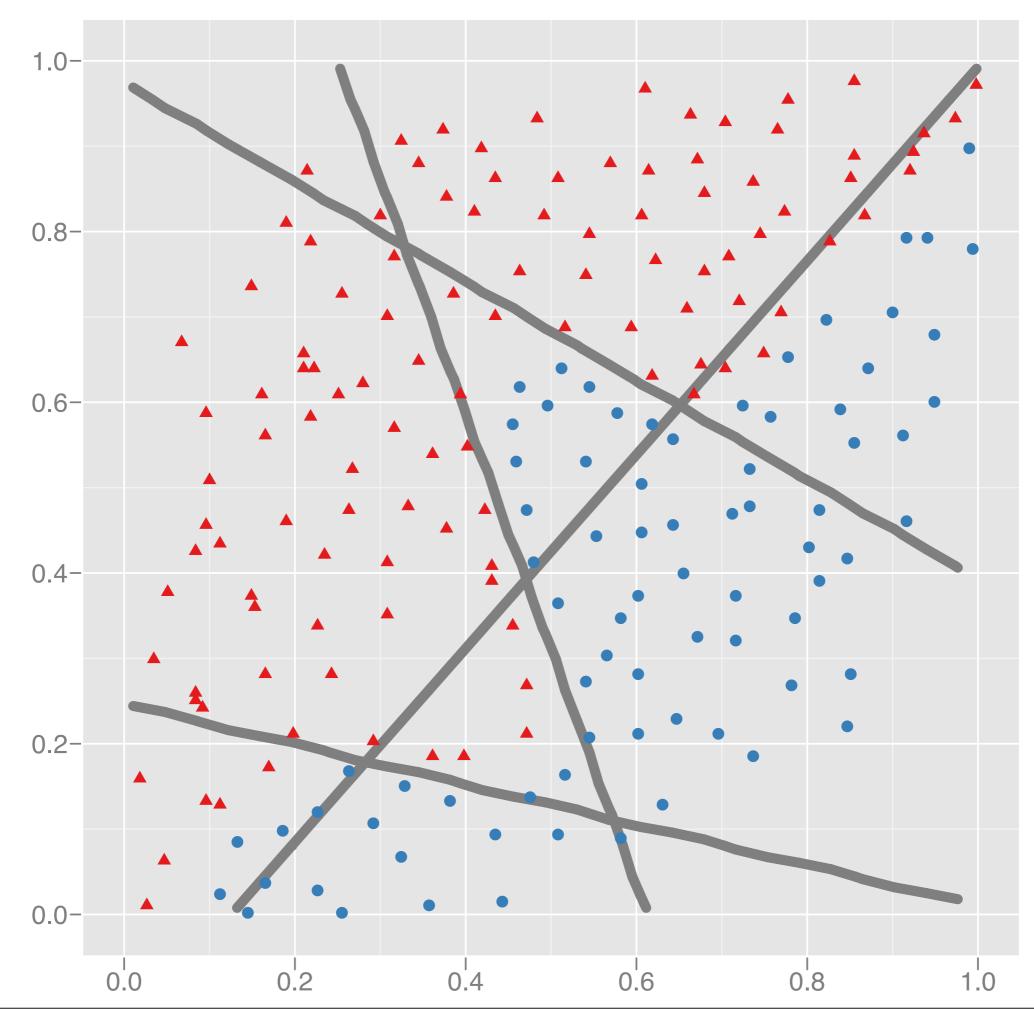


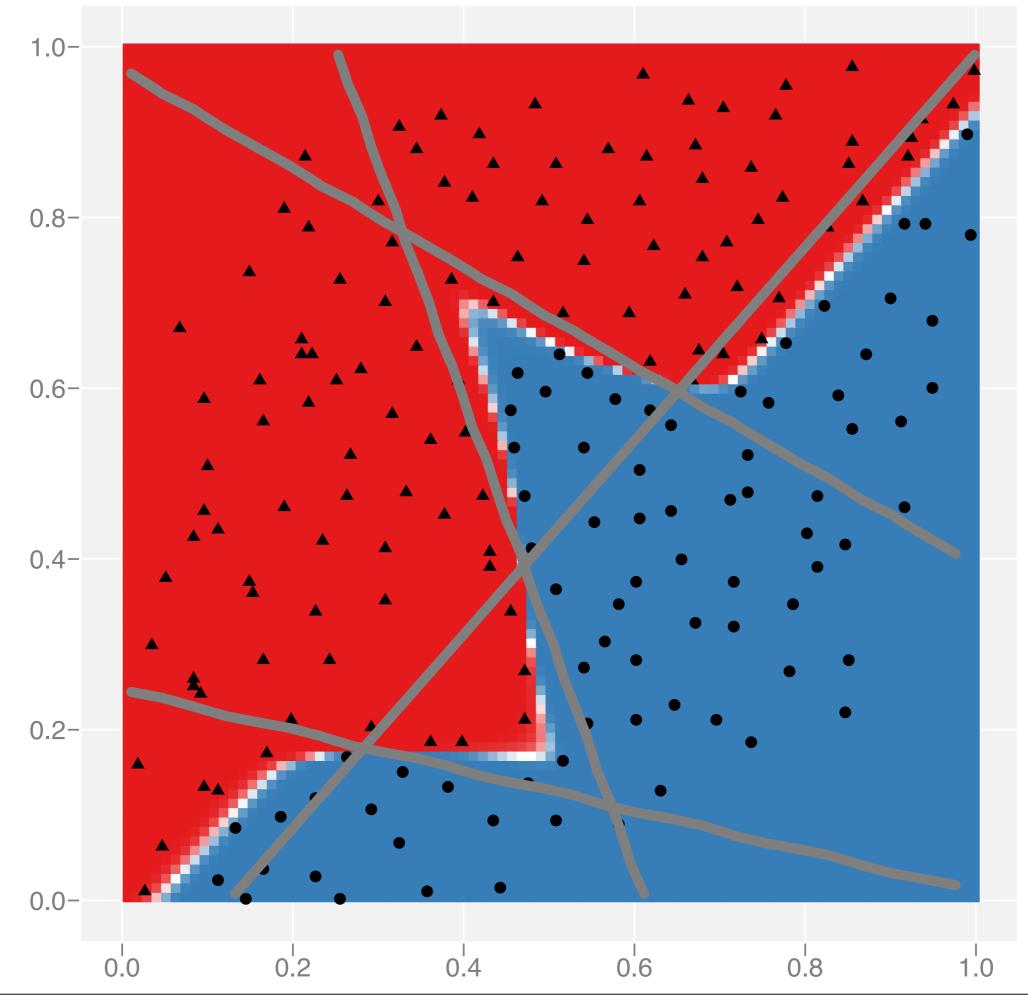


## Look at all members of the collection

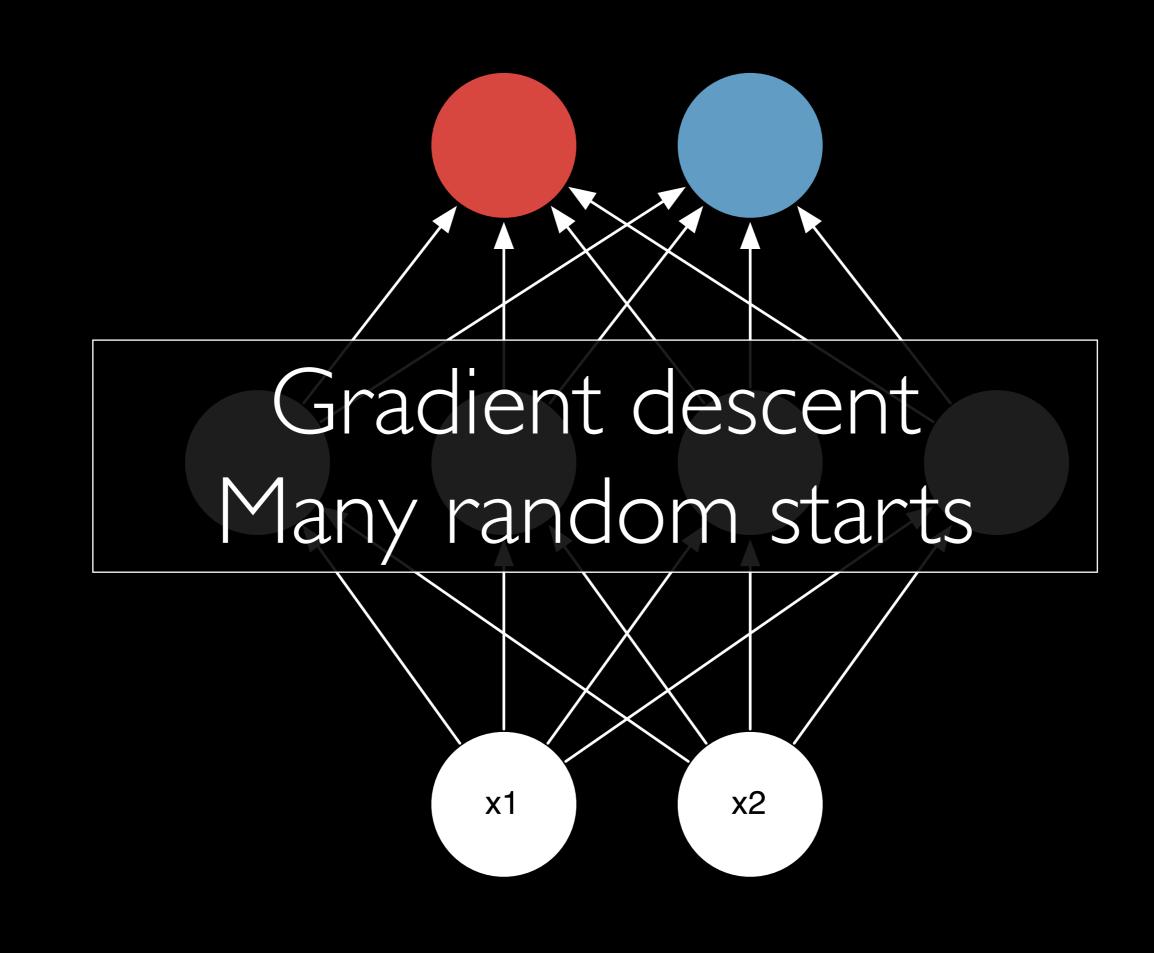


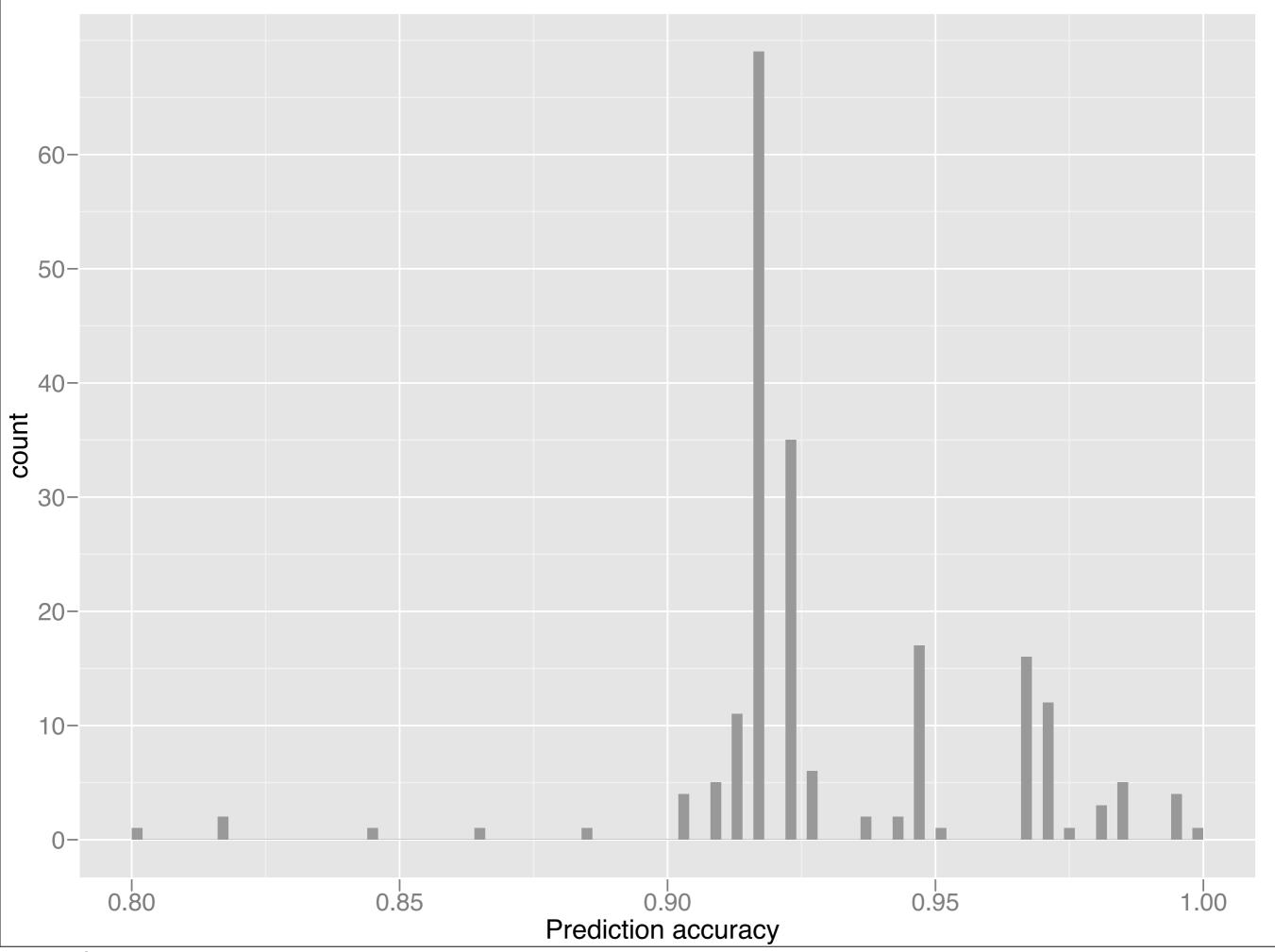


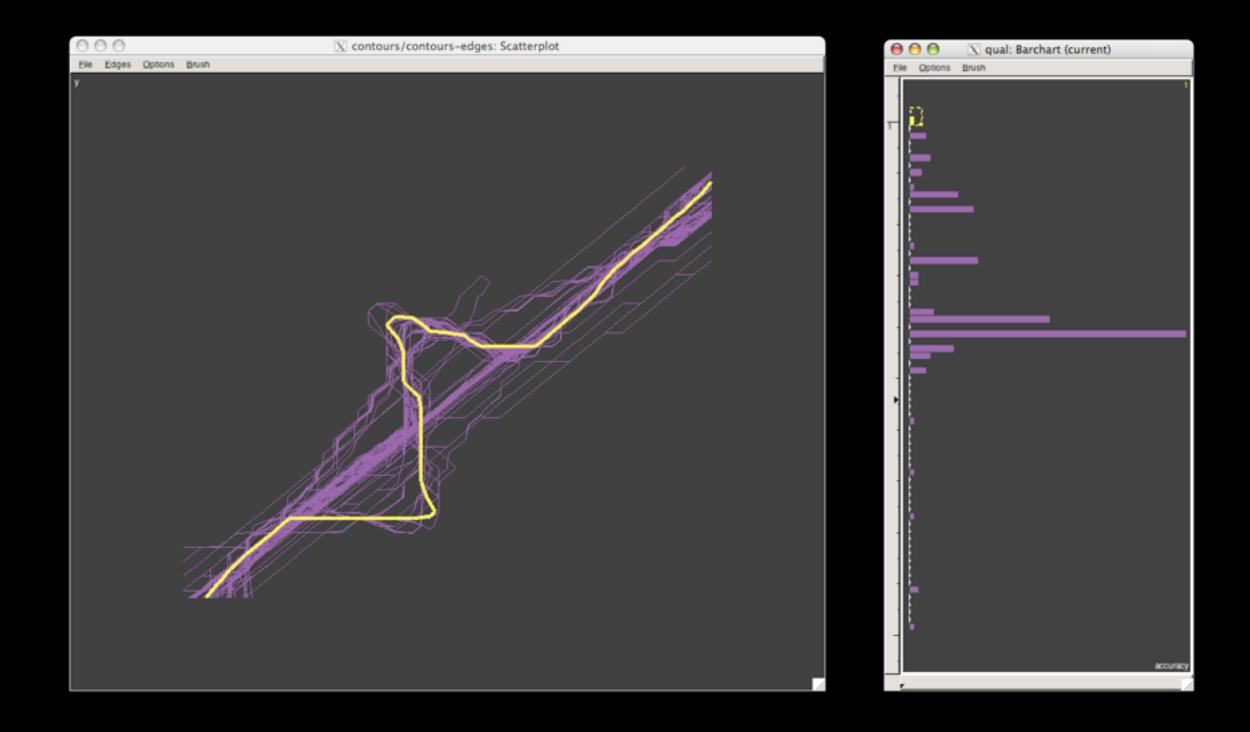




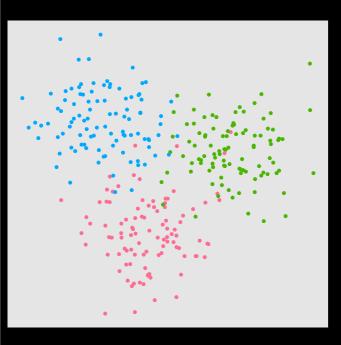
## How did I find that model?



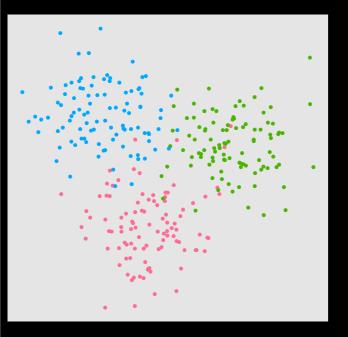


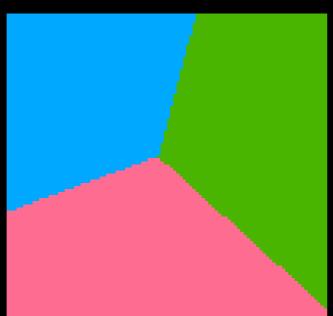


#### Input



#### Input Prediction

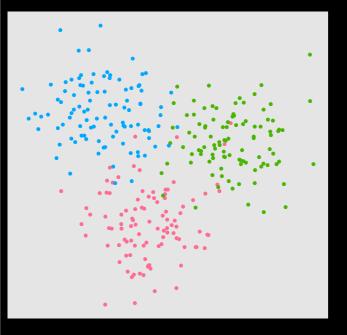


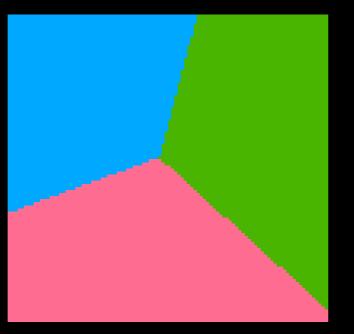


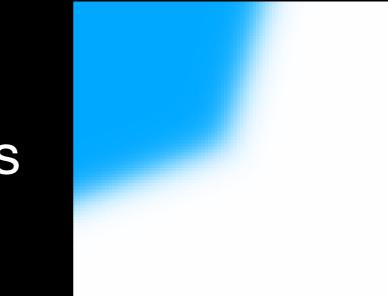
#### Input

#### Prediction

#### Probabilities





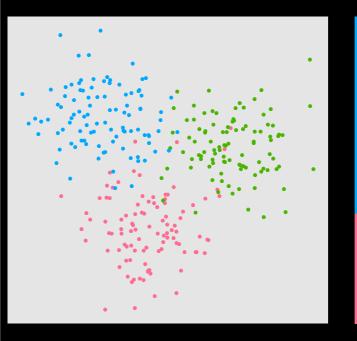


Most also provide class membership probabilities f:  $\mathbb{R}^{p} \rightarrow [0,1]^{k}$ 

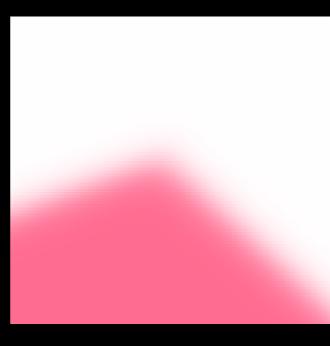
#### Input

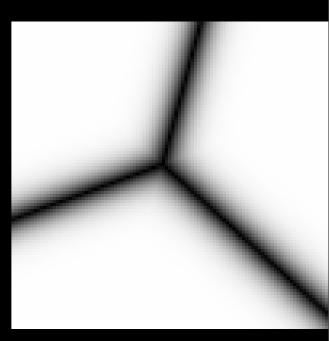
#### Prediction

#### Probabilities Advantage



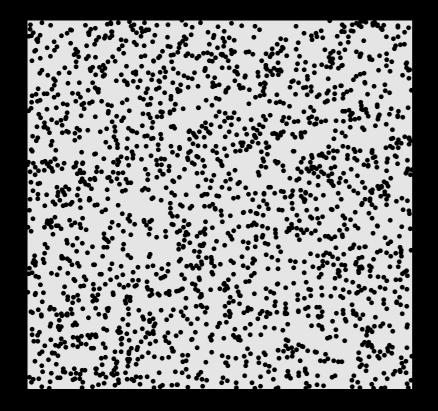




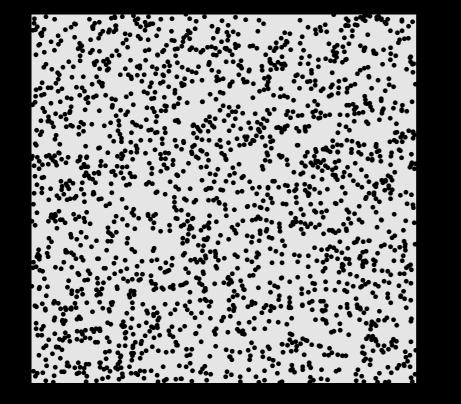


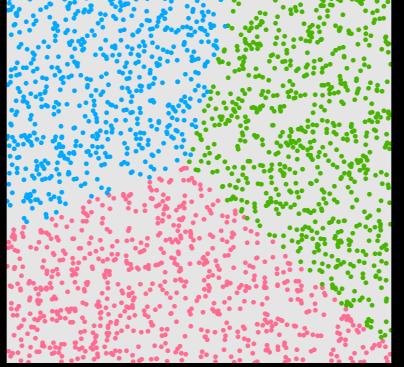
Most also provide class membership probabilities f:  $\mathbb{R}^{p} \rightarrow [0,1]^{k}$  P(best) -P(second best)

#### Random sample



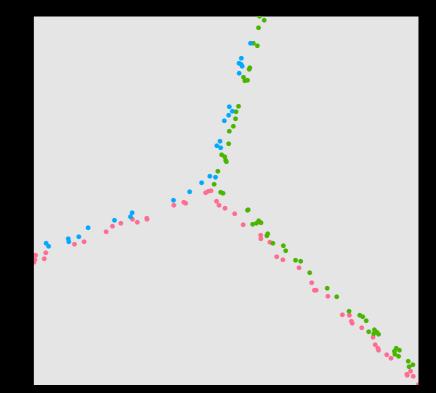
#### Random sample Classify

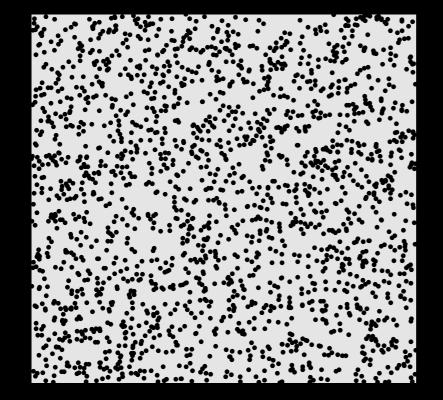


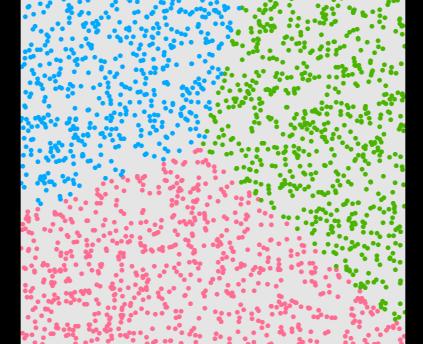


#### Random sample Classify

#### Low advantage

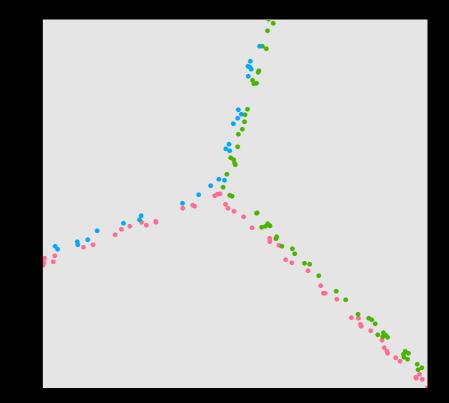


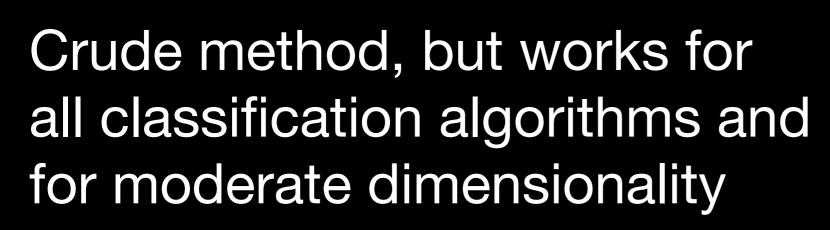




#### Random sample Classify

#### Low advantage





# **Ensembles of linear models**

Display the model in the data space

### Look at many members of a collection

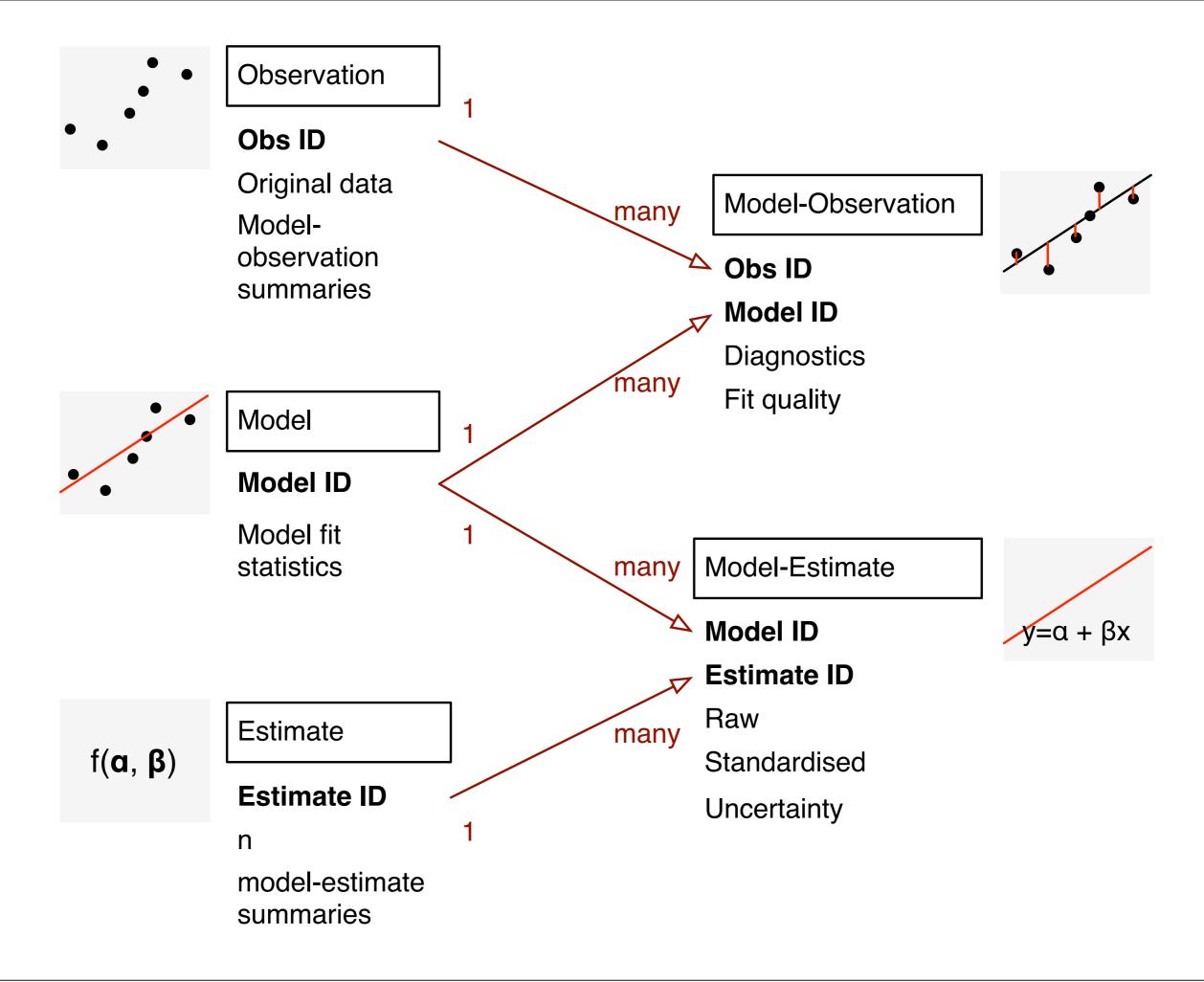
Explore the process of fitting, not just the end result

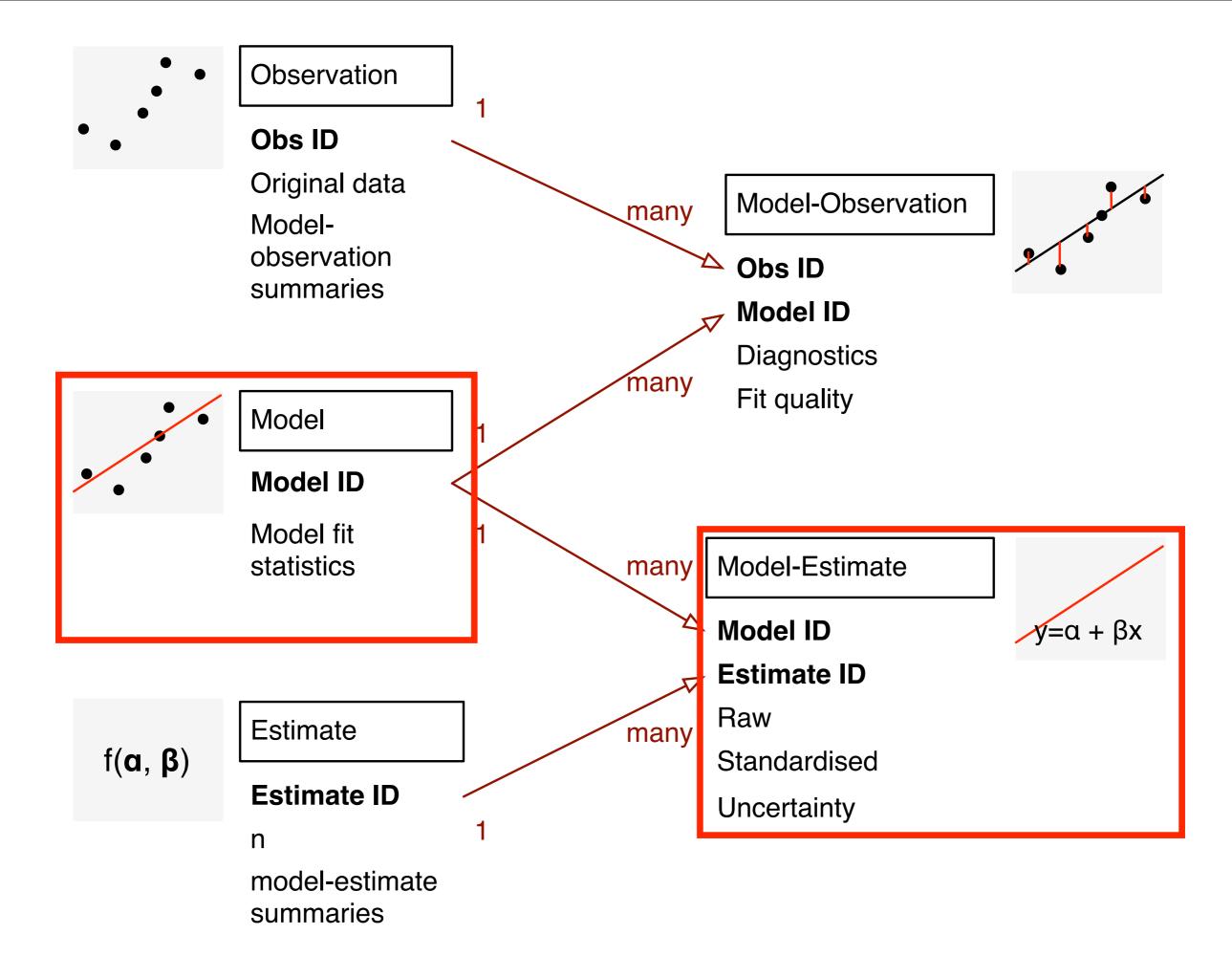
## Data

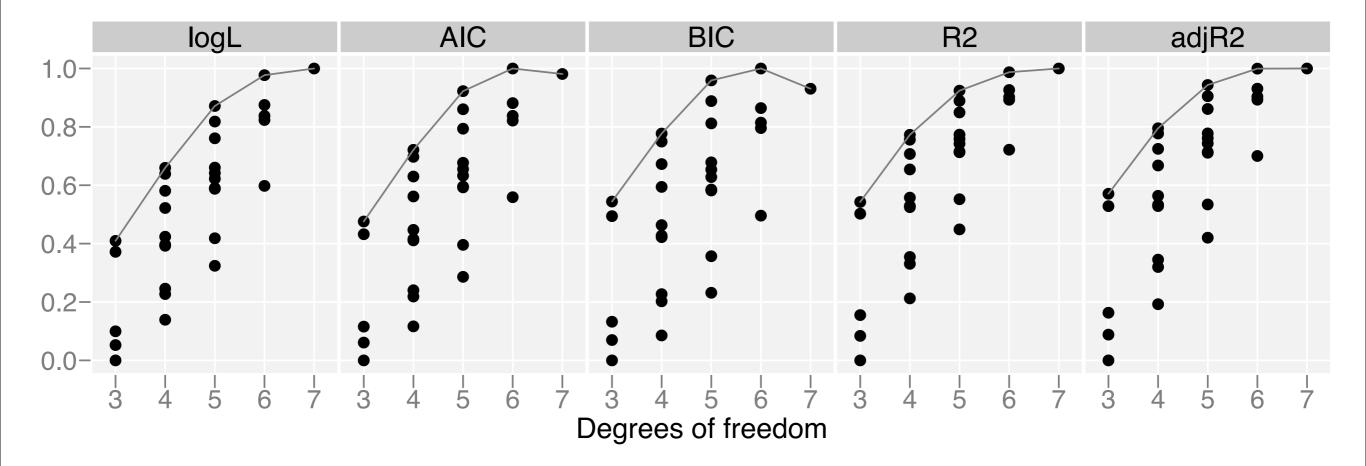
- Fertility in French-speaking Swiss provinces in the late 1800's
- Predict fertility based on:
  - proportion of agricultural workers
  - average performance on an army examination
  - amount of higher education
  - proportion of Catholics
  - infant mortality

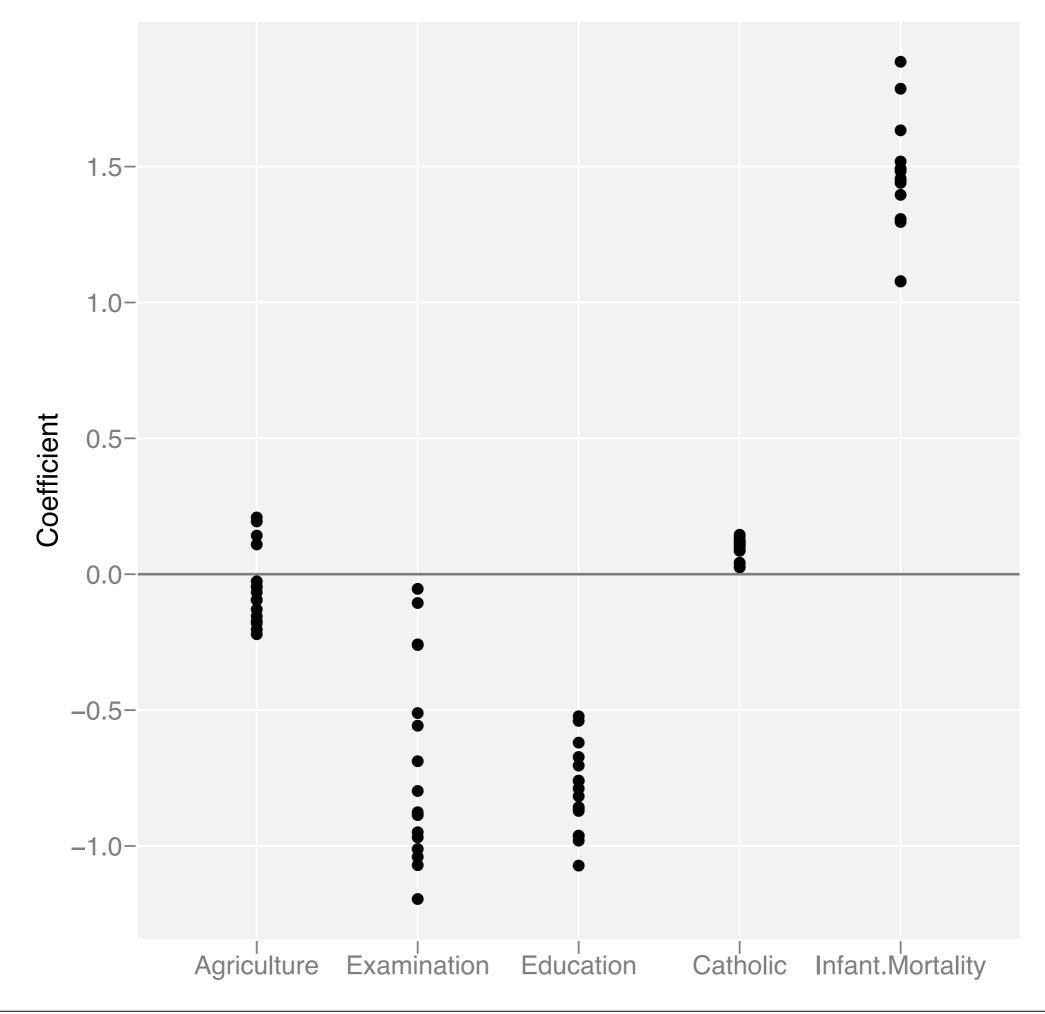
### Model

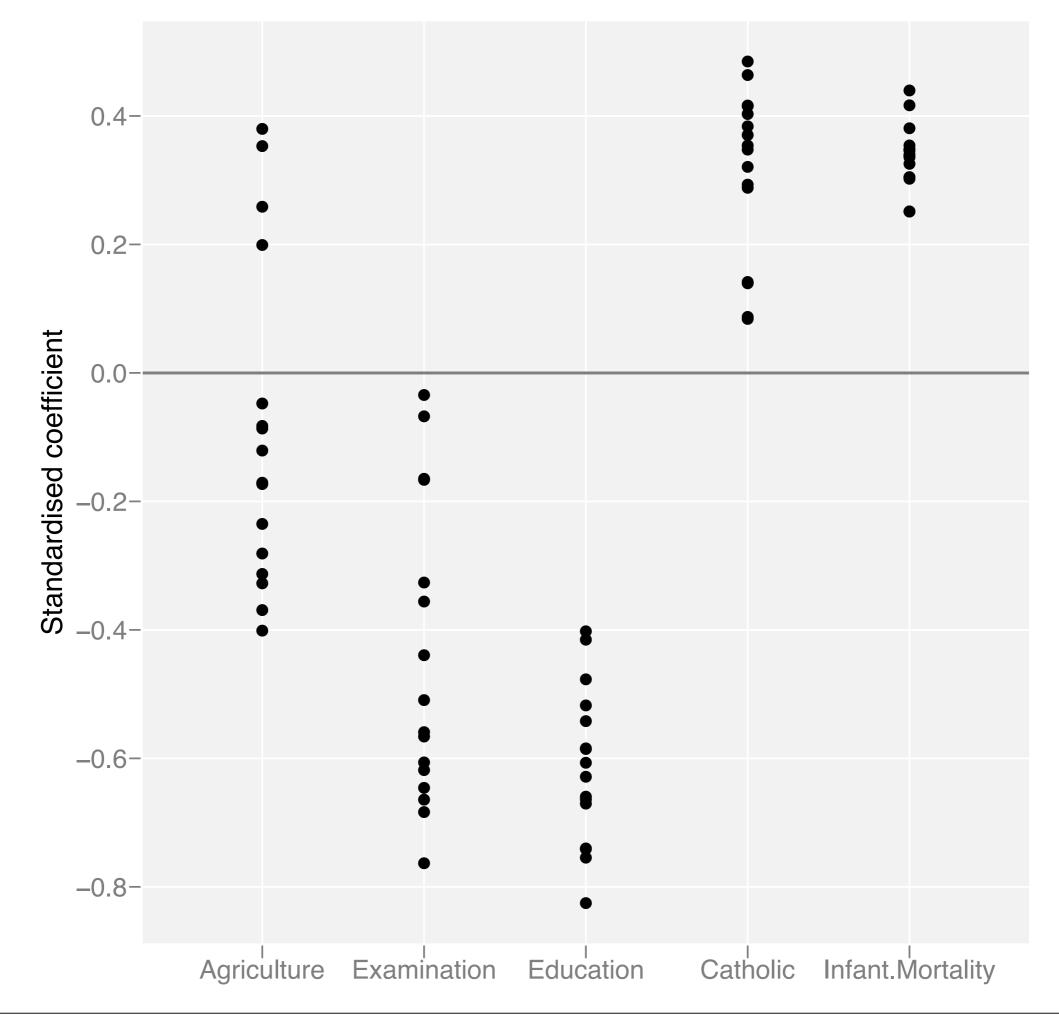
- Linear modes with all combinations of covariates (2<sup>p</sup> models)
- What can looking at all models tell us that looking at just a few can't?

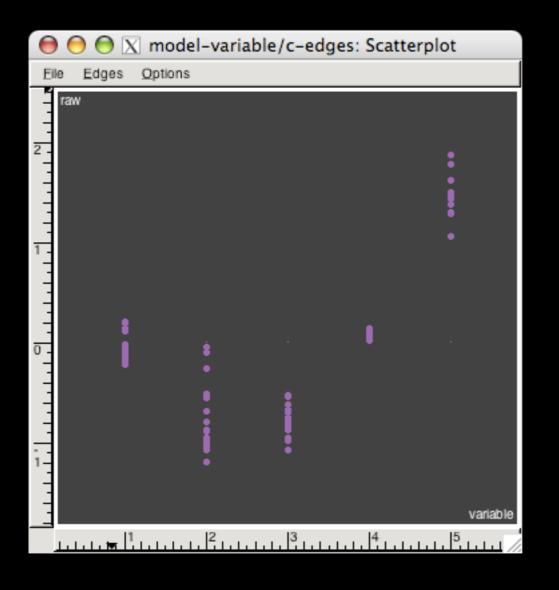












| 000  | X model: Scatterplot (current) |   |   |  |    |
|------|--------------------------------|---|---|--|----|
|      |                                |   |   |  |    |
| logL |                                |   |   |  |    |
|      |                                |   |   |  |    |
|      |                                |   |   |  |    |
|      |                                |   | : |  |    |
|      |                                | • |   |  |    |
|      | :                              | : |   |  |    |
|      |                                | • |   |  |    |
|      |                                |   |   |  |    |
| :    | :                              |   |   |  |    |
|      | :                              |   |   |  |    |
|      |                                |   |   |  |    |
| :    |                                |   |   |  |    |
| •    |                                |   |   |  |    |
|      |                                |   |   |  |    |
|      |                                |   |   |  | df |
|      |                                |   |   |  | 1  |

# Conclusions

# Other methods

- MANOVA
- Self-organising maps (clusterfly)
- Hierarchical clustering (clusterfly)
- Classification methods (classifly)
- Projection pursuit (tourr)

# The future

- Better iteration between modelling and visualisation
- Foundations to make interactive graphics easy to produce in R